

# Design, Implementation, and Optimization of MEGALib's Image Reconstruction Tool Mimrec

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## Abstract

MEGALib, the Medium-Energy Gamma-ray Astronomy library, is a toolset to simulate and analyze data from gamma-ray detectors. An integral part of MEGALib is its imaging tool Mimrec, which performs list-mode-likelihood image deconvolution. Mimrec has to handle data from coded masks, Compton cameras, and pair conversion telescopes with different response representations, on different imaging grids, with different deconvolution algorithms, etc. This versatility requires a highly modular and object-oriented design to avoid overhead and code redundancy. In addition, since some applications require close to real-time image reconstruction, great care has to be taken to optimize the library.

*Keywords:* MEGALib, Mimrec, image reconstruction, data analysis, gamma-ray detector, Compton camera

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## 1. Introduction

Gamma-ray detectors are utilized in many applications areas including astrophysics, nuclear medicine, and nuclear threat detection. The detectors implement a wide variety of imaging techniques such as coded masks, Compton scattering, pair conversion, and Laue diffraction. The underlying technology encompasses scintillators, time projection chambers, semiconductors (single volume, strip, and pixel detectors), as well as others. In addition, they can be arranged in a wide variety of geometries.

MEGALib, the Medium-Energy Gamma-ray Astronomy library [1], is a tool for simulating and analyzing measured and simulated data of many of these instruments for terrestrial and space applications. It encompasses the complete data analysis chain: simulations, detector response creation, event reconstruction, performance assessments, and of course image reconstruction. The freely available, open-source software package has a completely object-oriented design, is written in C++, and is based upon ROOT [2].

The image reconstruction is performed by the program Mimrec (Megalib IMAge REConstruction). A

brief overview of its overall design, some implementation details, its optimization, and some examples are presented in the next sections.

## 2. Design and Implementation

The measurement process of any gamma-ray telescope can be described in the following way:

$$D(\vec{d}) = R(\vec{d}; \chi, \psi, E) \times J(\chi, \psi, E) + B(\vec{d}) \quad (1)$$

Photons emitted from an energy-dependent intensity distribution on the sky  $J$  (with  $\chi, \psi$  as sky coordinates and  $E$  as energy) undergo the measurement process  $R$  and, together with some background  $B$ , are measured in the data space  $D$  with the parameters  $\vec{d}$ . The measurement process  $R$  completely describes the detector (absorption probabilities, detector noise, etc.) as well as all physical processes such as photo effect, Compton scattering, and pair creation.

The task of image reconstruction is to invert the measurement process and thus to determine the image  $J^{rec}(\chi, \psi, E)$  from the given measurements  $D(\vec{d})$  by utilizing the known response and background. Since no unique solution for this inversion problem exists, iterative approaches for the reconstruction of the image have to be chosen.

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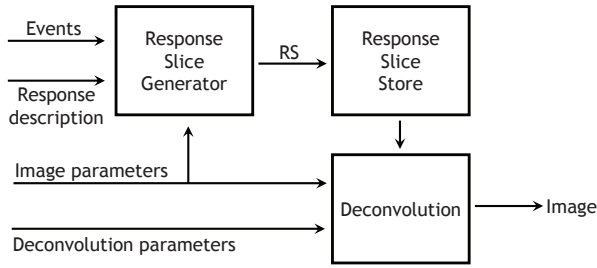


Figure 1: Basic layout of the imaging approach. See the text for details.

Mimrec implements list-mode-likelihood imaging methods such as the classic maximum-likelihood expectation-maximization approach [3]. In list mode, this method usually consists of two steps: first determine the response slices  $R|_{\vec{d}_m}$  for all measured data sets  $\vec{d}_m$ , and then perform the image deconvolution. Figure 1 shows the basic layout of the implementation. Before determining the response slices, the correct response description is chosen based on the event type (e.g. Compton with or without electron track). Then, for the given grid, the response slice  $R|_{\vec{d}_m}$  is determined or calculated based on the measured event data and grid position for all image bins. Next, the response slice is stored in an optimized way (e.g. sparse). When all response slices are determined, the deconvolution process is started using the response slices and some additional parameters. The result of the deconvolution is the reconstructed image. In Mimrec, the supervisor class MImager steers the image reconstruction and contains interfaces to set all parameters relevant for image reconstruction, which is usually done via a graphical user interface.

In order to be used in a wide variety of application scenarios, the image reconstruction approach has to be very versatile. Its most important design requirements include:

- Work for coded masks, Compton cameras with and without electron tracking, and pair-conversion telescopes in various instrument configurations
- Reconstruct images in Cartesian 2D and 3D as well as in astronomical coordinate systems
- Transparently handle different response representations
- Store the list-mode response slices in an optimized way to minimize RAM usage
- Transparently handle different deconvolution approaches

- Work close to real time for some application scenarios

In order to achieve the desired flexibility and to minimize code redundancy and overhead, a clear separation of all the different entities is required in the implementation: the data (e.g. the event types Compton and pair event), the response of the instrument, the calculated response slices, the image grid (e.g. Cartesian, spherical), and the deconvolution approaches.

In MEGALib several different event types exist which are all derived from the abstract base class MPhysicalEvent. They are distinguished by the primary physical process the original photon has undergone in the detector: MComptonEvent, MPairEvent, MPhotoEffectEvent, MMuonEvent, and MUnknownEvent for an event which can not be identified. The base class MPhysicalEvent contains data which is common to all events such as ID, event timing, the telescope orientation in Galactic coordinates, etc. The derived classes contain all the specific event data and implement functions to calculate high level information such as scatter angles in the case of Compton events.

Determining the response slices is an integral part of the image reconstruction in list-mode. This involves iterating over the image grid. In order to incorporate different image-grid types (e.g. Cartesian 2D and 3D, astrophysical coordinate systems) different classes have been implemented. Their base class MBackprojection manages the basic grid information, the event data, the response, and the geometry. The derived classes such as MBackprojectionCartesian and MBackprojectionSpheric handle the looping over the different grid types in a way that is optimized for the specific grid.

The various detector response classes are designed in an similar way. The base class MResponse provides interfaces to retrieve the response in a common way. For example, for Compton events without electron track the MBackprojection classes determine the distance of the image bin center to the Compton cone in degrees. The classes derived from MResponse contain the Compton response parametrized accordingly, but with different attention to detail. For example, MResponseGaussian provides a simple Gaussian approximation of the Compton cone shape, and MResponsePBRM retrieves the shapes of the Compton cones as a function of the measured data from a large response matrix generated by simulations. This implementation allows for the easy enhancement of Mimrec with additional, detector specific response descriptions.

In order to calculate absorption probabilities, which are required to determine the geometry dependent part

134 of the response, Mimrec uses Geomega (a description  
135 can be found in [4]), which is also part of MEGALib. It  
136 enables the handling of a wide variety of detector types  
137 and instrument geometries.

138 After the response slice is determined, it has to  
139 be stored for later image deconvolution. Usually the  
140 amount of RAM necessary to store all these slices is one  
141 of the limiting factors for image reconstruction. There-  
142 fore several optimized storage options have been imple-  
143 mented. All these distinct implementations have the ab-  
144 stract base class MBPData in common. This base class  
145 provides a common interface for data storage and re-  
146 trieval during the later deconvolution steps. The derived  
147 classes implement the concrete data storage in an opti-  
148 mized way. For example the class MBPDataImage just  
149 stores the data as a matrix of floats, and the class MBP-  
150 DataSparseImageOneByte stores it as a sparse matrix  
151 where the content is encoded in 8 bits (i.e. 256 inten-  
152 sity levels) plus a floating-point number for the absolute  
153 normalization.

154 Finally, the class MLMLAlgorithms is the base class  
155 for all list-mode likelihood deconvolution algorithms,  
156 which manages the image parameters, response slice  
157 handling, stop conditions for the iterations, and all com-  
158 mon data for the higher deconvolution algorithms. The  
159 derived classes, such as MLMLClassicEM and MLM-  
160 LOSEM handle the specific deconvolution steps.

### 161 3. Optimization

162 Several application scenarios demand close to real-  
163 time imaging. One scenario is terrestrial nuclear threat  
164 detection with instruments such as HEMI, the High-  
165 Efficiency Multimode Imager, a combined Compton  
166 and coded-mask telescope [5]. Another scenario is  
167 gamma-ray burst localization aboard gamma-ray satel-  
168 lites such as the envisioned GRIPS telescope, a com-  
169 bined Compton scattering and pair conversion telescope  
170 [6].

171 Although most parts of Mimrec have been optimized,  
172 the following discussion is restricted to the response  
173 slice calculation for Compton telescopes, since this is  
174 the most challenging part.

175 In general, several possibilities exist to optimize the  
176 image reconstruction speed. An obvious one is par-  
177 allelization on systems with multiple CPUs or cores.  
178 Mimrec is capable of performing the response slice cal-  
179 culation using multiple threads, each of which executes  
180 on a different CPU or core. For rather calculation in-  
181 tensive response descriptions, an almost linear scaling  
182 with number of threads is achieved. However, for sim-  
183 pler response descriptions, or when too many threads

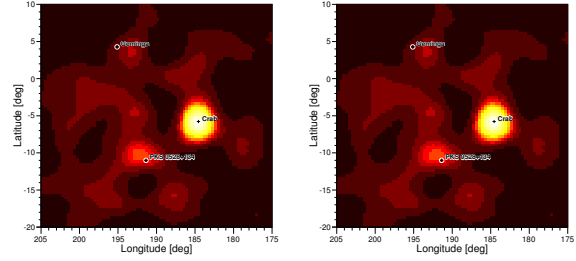


Figure 2: Galactic anti center with the pulsar Crab and the blazar PKS 0528+134, once calculated with the built-in mathematical function (left) and once using approximations (right)

184 are used, the calculation is often limited by reading the  
185 events from file or by synchronizing the threads.

186 Another option is the use of faster deconvolu-  
187 tion algorithms. Besides others, Mimrec implements  
188 the ordered-subset maximum-likelihood expectation-  
189 maximization approach [7].

190 A further option would be to delegate some of the cal-  
191 culations to the graphics processing unit (GPU). How-  
192 ever, since MEGALib has to be widely portable and  
193 independent from any specific hardware and operating  
194 system, this approach has not been followed.

195 Moreover, finding the optimum compiler options usu-  
196 ally also results in a performance improvement. Consid-  
197 ering only the response slice calculation using an Intel  
198 Xeon Processor E5520 (2.27 GHz) on Ubuntu 9.10, the  
199 reconstruction speed is optimized by the following com-  
200 piler options (here for gcc 4.3): `”-O3 -march=native  
201 -no-strict-aliasing”`. This results in roughly 20% im-  
202 provement compared to the standard `”-O2”` option. Of  
203 course the improvement depends on the compiler ver-  
204 sion and the given CPU.

205 The most promising approach is, however, to opti-  
206 mize the code itself. A general approach is to use a pro-  
207 filer to uncover and eliminate bottlenecks in the code.  
208 With this approach, two critical areas can be identified:  
209 the used mathematical functions and the looping over  
210 the image grid.

211 The built-in mathematical functions provide much  
212 higher accuracy than needed for the final steps of im-  
213 age reconstruction (e.g.  $\sim 16$  digits for double). Al-  
214 though the built-in functions are highly optimized, re-  
215 placing them with simpler approximations is advanta-  
216 geous. The most frequently used, time-intensive func-  
217 tions are `acos()`, `exp()`, and `1/sqrt()`. While the first two  
218 are replaced by approximations found in [8], the latter  
219 is exchanged with the so called `”Quake-III”` or `”Fast in-  
220 verse square root”` algorithm [9]. The achievable im-

221 improvement varies with the used CPU, compiler, image-  
222 grid size, response, and application scenario. Figure 2  
223 shows the Galactic anti center with the pulsar Crab and  
224 the blazar PKS 0528+134 as measured with COMPTEL  
225 [10], once calculated with the built-in mathematical  
226 functions (left) and once using approximations (right).  
227 While the speed improvement is 45%, the intensity dif-  
228 ference is only  $4 \times 10^{-5}$ , which is negligible compared to  
229 an overall uncertainty of at least several percent.

230 Another important optimization is to accurately de-  
231 termine where to start the response calculation on the  
232 grid. Usually most of the bins on the image grid can  
233 be skipped, because the probability that the detected  
234 photon originated from these bins is below a certain  
235 threshold. For this task all response classes derived  
236 from MResponse provide a minimum and maximum angle  
237 around the measured Compton scatter angle, outside  
238 of which the response is below a certain threshold and  
239 thus can be neglected. In spherical coordinates the bins  
240 which fall within that range can be determined using  
241 spherical trigonometry. The performance improvements  
242 depend mostly on the detector response and the bin size,  
243 and range from 0% when the response covers the whole  
244 sky (because, e.g., the response includes incomplete ab-  
245 sorption) to several 100% improvement for very narrow  
246 Compton cones. Furthermore, since the response slice  
247 is in many cases a sparse matrix, it should be handled  
248 from beginning to end as a sparse matrix to save further  
249 CPU cycles.

250 Finally, an overall performance test has been per-  
251 formed using simulations of the High-Efficiency Mul-  
252 timode Imager (HEMI). Typically, a large 1-m<sup>2</sup> instru-  
253 ment [11] measures a few thousand Compton events  
254 per second. Using a Gaussian approximation for the  
255 response of Compton events, and performing the im-  
256 age reconstruction on a 2-degree grid (angular resolu-  
257 tion  $\sim 5^\circ$ ), results in a reconstruction performance of at  
258 least 7,500 Compton events per second and per CPU  
259 core for the used Intel Xeon E5520 CPU. This is more  
260 than enough for real-time imaging with HEMI.

261 For astrophysical real-time applications such as a  
262 gamma-ray burst mission such as GRIPS, the situation  
263 also appears favorable. Although the performance of  
264 space-grade computer systems is significantly below to-  
265 days state-of-the-art hardware, only several tens of good  
266 (i.e. pre-selected) Compton events are necessary for the  
267 localization of a gamma-ray burst.

#### 268 4. Summary

269 Mimrec is a versatile, highly-optimized image recon-  
270 struction tool. It can be applied to a wide variety of

271 gamma-ray detectors on ground and in space and han-  
272 dles various event types (coded mask, Compton scatter-  
273 ing, pair creation), on various image grids, using differ-  
274 ent response representations, and different deconvolu-  
275 tion algorithms. It has been optimized to provide close  
276 to real-time imaging performance for some applications  
277 scenarios.

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